Curriculum Vitae Hamid Manouchehri

Education:

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Master of Science in Mechatronics Engineering University of Tehran The initial data of the second				
Thesis title: A Model-Based Control System for Bi-Manual Object Manipulation (<u>link</u>) Related Passed Courses: Advanced Math, Mechatronics, Dynamics, Advanced Robotics, Nonlinear & Fuzzy Control, Machine Vision (audited), Bio-inspired Computing				
 Bachelor of Science in Electrical Engineering (Control Engineering) University of Kashan Project title: Design and Manufacturing of Pneumatics Table of Instrumentation Lab (link) Related Passed Courses: Calculus, Computer Programming (C), Circuit Theory, Electronics & Microprocessor, Digital Signal Processing, Communication Systems, Linear, Advanced & Digital Control, Linear Algebra, Industrial Control, Instrumentation, Industrial Automation 				
			esearch Interests:	
 Legged Locomotion Machine Vision Manipulators Manipulators Mechanical Design & Modeling Rehabilitation Robotics BMS & IOT 				
eaching Experience:				
Teacher Assistant Instructor: <u>Dr. Farzan Rezaei</u>	Spring 2017			
	Spring 2017			
Instructor: <u>Dr. Farzan Rezaei</u> Course: Digital Logic and Computer Design Responsibilities: Teaching applications of ' <i>Proteus Design Suite'</i> in digital circuit analysis	Spring 2017			
 Instructor: <u>Dr. Farzan Rezaei</u> Course: Digital Logic and Computer Design Responsibilities: Teaching applications of '<i>Proteus Design Suite</i>' in digital circuit analysis and design, and mentoring the students. roject and Research Experiences: Implementation of Ant Colony Optimization (ACO) in Vehicle Routing Problem and Genetic Algorithm in a Decision-Making Problem. (link) Instructor: <u>Dr. Masoud AsadPour</u> 	Spring 2017 Apr 2021			
 Instructor: <u>Dr. Farzan Rezaei</u> Course: Digital Logic and Computer Design Responsibilities: Teaching applications of 'Proteus Design Suite' in digital circuit analysis and design, and mentoring the students. roject and Research Experiences: Implementation of Ant Colony Optimization (ACO) in Vehicle Routing Problem and Genetic Algorithm in a Decision-Making Problem. (link) Instructor: <u>Dr. Masoud AsadPour</u> Course: Bio-inspired Computing Implementation of a PID Controller by Fuzzy Logic (Self-organizing Fuzzy PID Controller) Instructor: <u>Prof. Aghil Yousefi Koma</u> 				
 Instructor: <u>Dr. Farzan Rezaei</u> Course: Digital Logic and Computer Design Responsibilities: Teaching applications of 'Proteus Design Suite' in digital circuit analysis and design, and mentoring the students. roject and Research Experiences: Implementation of Ant Colony Optimization (ACO) in Vehicle Routing Problem and Genetic Algorithm in a Decision-Making Problem. (link) Instructor: <u>Dr. Masoud AsadPour</u> Course: Bio-inspired Computing Implementation of a PID Controller by Fuzzy Logic (Self-organizing Fuzzy PID Controller) 	Apr 2021			
 Instructor: <u>Dr. Farzan Rezaei</u> Course: Digital Logic and Computer Design Responsibilities: Teaching applications of '<i>Proteus Design Suite</i>' in digital circuit analysis and design, and mentoring the students. roject and Research Experiences: Implementation of Ant Colony Optimization (ACO) in Vehicle Routing Problem and Genetic Algorithm in a Decision-Making Problem. (link) Instructor: <u>Dr. Masoud AsadPour</u> Course: Bio-inspired Computing Implementation of a PID Controller by Fuzzy Logic (Self-organizing Fuzzy PID Controller) Instructor: Prof. Aghil Yousefi Koma Course: Fuzzy Systems: Theory and Control Simulation of a Wheeled Inverted Pendulum by Partial Feedback Linearization (link) Instructor: <u>Dr. Khalil Alipour</u> 	Apr 2021 Jan 2021			

Fanavard Competition of Sharif University of Technology

→ As a team, we were planning to run an E-Commerce **startup** to provide online repairing services.

<u>Skills:</u>

- Robotic Softwares / Middlewares: Robot Operating System (ROS 1), RBDL toolkit, RViz, MOVEit, OpenCV (familiar), RoboDK (familiar)
- > Programming Languages: C (Professional), Python, C++, C#, bash script, XML, Lua
- > Technical Softwares: MATLAB (Script, Simulink, GUI), Proteus, Altium Designer, Docker
- > Mechanical Softwares: SolidWorks, FreeCad (familiar), MCS Adams
- Embedded Systems: MPLAB X IDE (PIC MCUs), Keil (ARM MCUs), CodeVision (AVR MCUs), Raspberry Pi Pico MCU, Arduino IDE, Raspberry Pi (Raspbian OS), NodeMCU, SIM800L GSM
- Version Control Tools: Git, GitHub, GitLab
- Linux: LPIC-1 (Linux Professional Institute)

Working Experience:

 Electronics Engineer, Part-time (link) Employer: Parmis Smart Home Business: Design of smart devices for BMS (Building Management System) Responsibilities: Embedded system designer, Firmware developer of PIC MCUs 	Isfahan, Iran Mar – Dec 2021
 Electronics Engineer, CAD Designer, Part-time (link) Employer: Kanda Idea Company Responsibilities: Research and Development, Designing a box for some electrical devices with SolidWorks 	Tehran, Iran Feb – Nov 2020
 Control & Instrumentation Laboratory, Internship Employer: University of Kashan. Responsibilities: Design & Manufacturing a pneumatic table with fluidsim 	Isfahan, Iran Jun – Aug 2017

Certificate:

Robot Operating System (ROS): Basic, offered by PISHROBOT, approved by ROBOTISSep 2021Covered topics: Basic concepts of ROS 1 (melodic), navigation of TurtleBot in RViz as final
project.Sep 2021

anguage Proficiency:				
Exam	Overall Score	Scores		
TOEFL iBT (Mar 12, 2023)	-	-		
GRE General (Apr 17, 2023)	-	-		

References:

Dr. Mohammad Shahbazi	M.Sc. Supervisor	Assistant Professor School of Mechanical Engineering Iran University of Science and Technology Email: <u>shahbazi@iust.ac.ir</u> , <u>HomePage</u> , <u>Google Scholar</u>
Dr. Bahrām Tarvirdizadeh	M.Sc. Supervisor	Associate Professor Faculty of New Science and Technology University of Tehran Email: <u>bahram@ut.ac.ir</u> , <u>HomePage, Google Scholar</u>
Dr. Alireza Hadi Hosseinabadi	M.Sc. Advisor	Associate Professor Faculty of New Science and Technology University of Tehran Email: <u>hrhadi@ut.ac.ir</u> , <u>HomePage</u> , <u>Google Scholar</u>

last edited: May 26, 2023